

iMod6

Description:

This full-featured programmable DIN-Rail I/O module is specifically designed by our engineers for full compatibility with HvacCore software products.

In conjunction with the HvacCore suite, it provides unique features, full programmability, easy Modbus integration, all at one of the best performance/price ratio available on the market.

Highlights:

-Licensed for HvacCore programming -Standard DIN-Rail mounting enclosure -10 AI, 4 AO, 4-20mA option, 8 relays -Real Time Clock -Two RS485 network ports, adjustable baud rate -High performance MCU



Technical data:

iMod68 relays x 3A @ 24VAC, 10
AI, jumper selectable (Therm, 0-10V, 4-20ma) 12 bit resolution, 4 AO,
jumper selectable (0-10V, 4-20ma) 10 bit resolution. Operating
temperature
voltage12~24VAC/DC ±20%, 50-60Hz. Nominal
power consumption100mA at 24VDC.
Relay contacts rating3A @ 24VAC. UL
File No.: E238496Certified to CAN/CSA-C22.2 No. 14: UL
File No.: E238496. Operating Environment0 ~ 99% humidity
non condensing. Plastic Housing Material Flammability rating UL 94V0
file E194560. Real Time Clock Outputs can be manually switched to ON,
OFF, AUTO Supports standard Modbus/RTU protocol Two RS485
network ports, adjustable baud rate
ColourWhite, RAL9003-Signal White.





iMod6 connections and board:

Inputs:



Outputs:







Analog output jumper settings:



Analog input jumper settings:





Wiring Diagram:



One Year Guarantee and Limitation of Liability:

Hvac-Controls Kft. guarantees to the original purchaser that this product is free from defects in both material and workmanship under normal use and service within one (1) year from the date of shipment from the factory or from its official sales channel to the original purchaser. The liability of Hvac-Controls Kft. under this guarantee shall not in any case exceed the cost of correcting defects in the product of supplying replacement product as herein provided and upon the expiration of the guarantee period all such liability shall terminate.



Programming your device: ControlCore quick tutorial

The following tutorial will walk you through the creation of a simple HvacCore project. No actual embedded hardware is required, we will use simulation mode. Upon completion you will have created a typical control algorithm for a series of embedded devices and you will be able to actually test it out using HvacCore hardware simulation facility. The final project will look something like the display shown below.

ControlCorePro Device Configu Project Device Blocks Help	urator ()	<u>_ ×</u>
comm	Identification HW Configuration Program History Sequence of operation Q Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Q Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation Image: A sequence of operation <	

Programming your device: Starting a new ControlCore project

When you start HvacCore you will be presented with a blank workspace. The first step will be to create a new project, select **Project -> New Project...** from the main menu at the top of the window.

ControlCore Device Configur	ator ()			
roject Device Blocks Help				
New Project				
Open Project K	Previous Projects			
	Project Name	Last Used	Last Modified	Pat 🔺
Save Project	demo 1	January-10-11	April-15-10	C:V
SaveProject As	mytemp	January-07-11	January-07-11	C:V
Export Project (CSV)	demo 1	January-03-11	December-28-10	C:V
Export (10)oct (201)	myheat	December-14-10	January-03-11	C:V
Exit	dock	December-08-10	November-08-10	C:V
	new	December-08-10	unknown	file
	SDItest temp-1	December-08-10	unknown	file



The new project's icon will appear on the left side of the window. By clicking on the icon, you will see the project's settings on the right. The default connection type is a local serial port. For the purpose of this tutorial, we will use the "Simulated" option, with no device connected.

ControlCorePro Device Co	nfigurator ()	
Project Device Blocks Help	COMM Configuration Comm Name comm C Local Comm Port Remote Ethernet Gateway Image: CatNet C EIN Moz Wireless TCP//P Server Gateway	Apply
	Network Scan Select All Scan Project Devices Scan Range	

Programming your device: Add devices to your project

You can add devices to your new project by selecting Device -> Add Device(s) from the top menu bar.

ct [Device Blocks Help		
	Add Device(s)		
ortł	Delete Device 45 (Del)	ification	
E	Cut Device	Name COM1 Apply	
2	Copy Device Paste Device	4 Configuration	
	Copy Multi Devices Export Block List Export Modbus Addresses	Normal Mode C Remote Ethernet Gateway C CatNet Comm Port V Available Ports Only Baud rate	
	Print Program	Start COM1 19.2K	¥

This will display the dialog box shown below. Select the type of device to add from the left selection list and then enter the device's address in the text box at the bottom. You can add several devices in one step by entering several device addresses in the text box. Note that valid addresses are 1..253. Addresses 0 and 255 are reserved and 254 is a special universal address. When a device sees the address 254 it always responds, hence it is VERY important that you never use 254 on an RS485 network with more than 1 device connected. Generally 254 is used to access a device where the actual address is not known. For the purpose of this tutorial, we will add a single iMod6 device to our project, at address 1.

Mod6 Temco Tstat5A Temco Tstat5B Temco Tstat5B2 Temco Tstat5C Temco Tstat5C Temco Tstat5C Temco Tstat5E Temco Tstat6 Temco T3-810A Temco T3-8130	
Temco Tstat5A Temco Tstat5B Temco Tstat5B Temco Tstat5C Temco Tstat5D Temco Tstat5D Temco Tstat5D Temco Tstat6 Temco Tstat6 Temco T3-8IDOA Temco T3-8IJOO	
Temco Tstat5B Temco Tstat5C Temco Tstat5C Temco Tstat5D Temco Tstat5D Temco Tstat5E Temco Tstat6 Temco T3-8IOA Temco T3-8I 3O	
Temco Tstat5B2 Temco Tstat5C Temco Tstat5C Temco Tstat5E Temco Tstat56 Temco Tstat6 Temco T3-8IOA Temco T3-8I 30	
Temco Tstat5C Temco Tstat5D Temco Tstat5E Temco Tstat6 Temco T3-8IOA Temco T3-8I13O	
Temco Tstat5D Temco Tstat5E Temco Tstat6 Temco T3-810A Temco T3-8113O	
Temco Tstat5E Temco Tstat6 Temco T3-8IOA Temco T3-8I130	
Temco Tstat6 Temco T3-8IOA Temco T3-8I130	
Temco T3-8IOA Temco T3-8I130	the second se
Temco T3-8I13O	
Tenneo To orroo	
Temco T3-32I	
Temco PM-5E	
Temco T34AO	
emco T3-32I emco PM-SE emco T34AO	



Programming your device: Device Hardware Configuration

The devices created in the previous step are now shown on the left hand side tree view. Selecting one of the devices displays its configuration tabs on the right. The HW Configuration tab allows access to the device's hardware configuration, (i.e. IO pins and display). Clicking on the selected pin will sequentially toggle through the available options for that pin. Select each pin and setup the pin configuration shown below.

ControlCore Device Configurat	Tidentification [HW Configuration] Program Sequence of operation	<u>- IOI ×</u>
	$iMod6$ $RS485 \rightarrow 1$ $RS485 \rightarrow 2$ $GND \rightarrow 3$ $I6$ $A \rightarrow 4$ $I7$ 5 $I8$ $PD0$ 6 $I9$ $I9$ 22 22 10 23 11 24 25 13	



Programming your device: Device Programming

The Program tab allows access to the device's embedded program, from this tab you can create the actual control algorithm that will be downloaded into the device. Initially, the programming tab is set to the edit mode which is indicated by the selection of the arrow cursor icon at the top. To create a program you will select function blocks from the top row of icons; drop them in the workspace; and then double-click them to access each block's parameter definition dialog. Connections among the blocks are done by setting the input parameter selections on each block's parameter definition dialog. Note that the I/O pins previously defined on the Hardware Configuration tab appear as blocks on the left or right hand side of the workspace, left hand for inputs, right hand side for outputs.



For the purpose of this tutorial we will create a simple temperature controller.









Step Insert an AV function block. This type of block simply holds an user settable analog value. It will be the temperature set-point. Its name can be changed to "SP" by double-clicking the block and modifying the "Name" field.

Now we will do the input connections to the PID1 function block. Double-click the PID1 function block to invoke its parameter definition dialog and set the "Input" parameter to "Tint" the temperature input block. Similarly, set the PID1's

"Set Point" parameter to "SP", the block we created in the previous step.

Step 4

Step

5

Step

3

element. We assume that we have a power amplifier compatible with a 0 to 5V signal. To connect it to the PID control output, double-click the AO1 block to invoke its parameter definition dialog and set the "Input" parameter to "PID1".

We will use the analog output block AO1 to drive the heater

Alternatively, if we do not have a linear power amplifier to drive the heater element we can drive it via a PWM (Pulse Width Modulation) block. To add it, simply select and drop a PWM type function block and connect its "Input" parameter to "PID1". Then connect its output to one of the digital output blocks, DO1, for example.



Congratulations you have successfully created a temperature control program for your device. This program can now be downloaded and run on the target embedded device. Your final program should look like the one shown below.





Programming your device: Run Mode & Live Monitoring

Once you have completed a program you can download it into the embedded device and monitor it in real-time. To do this, simply change the Program tab mode from edit mode to Run mode by selecting the run mode icon.



When you select the monitor mode the system will automatically download the current program into the selected device. It will pop up a dialog to request that you confirm, select OK to continue. While in RUN mode you can add monitors to any one of the connection lines to view or set its current value in real-time. To add a monitor hover over a connection with the mouse, a monitor will appear automatically. If you move away the monitor disappears. To make a monitor remain permanently click on the connection line before moving away. There are two types of monitors, analog monitors that show the current value and digital monitors that show the state (ON or OFF). To remove a monitor, click the X on the upper right hand side.



To set a value on an analog monitor, click and drag the mouse along the bar graph or type the desired value while the monitor is highlighted. For digital monitors the state can be toggled by clicking on the LED or by pressing the space bar while the LED is highlighted. When hovering over a block in run mode, a box will indicate the block's Modbus register, if defined. Also, the function block's dialog box information can be displayed in run mode, but all fields are read only. Blocks can be moved around for a better view.